Artifact for “GenTree: Using Decision Trees to Learn Interactions for Configurable Software”

KimHao Nguyen and ThanhVu Nguyen
University of Nebraska-Lincoln, USA
{kdnguyen,tnguyen}@cse.unl.edu

Abstract—This document describes the artifact package accompanying the ICSE’21 paper “GenTree: Using Decision Trees to Learn Interactions for Configurable Software” [1]. The artifact includes GenTree source code, pre-built binaries, benchmark program specifications, and scripts to replicate the data presented in the paper. Furthermore, GenTree is applicable to new programs written in supported languages (C, C++, Python, Perl, Ocaml), or can be extended to support new languages easily. GenTree implementation is highly modular and optimized, hence, it can also be used as a framework for developing and testing new interaction inference algorithms. We hope the artifact will be useful for researchers who are interested in interaction learning, especially iterative and data-driven approaches.

I. INTRODUCTION

Testing, debugging, and analyzing highly configurable systems are challenging because of the exponentially large configuration spaces—in the worst case, every combination of option settings can lead to a distinct behavior [2]–[5]. The configuration space explosion presents real challenges to software developers because faults are often visible under only specific combinations of configuration options. Static analyses are difficult because of the path explosion problem and usage of external libraries that are difficult to model precisely.

An interaction for a location is defined as a logically weakest formula over configuration options such that any configuration satisfying that formula would cover that location. The GenTree [1] interaction learning algorithm is inspired by the iterative and dynamic approach of iGen [6] but can discover interactions under arbitrary boolean formula by leveraging the expressive power of decision trees. This document describes the reusable artifact package accompanying the paper, which includes source code, pre-built binaries, benchmark program specifications, and scripts to replicate the evaluation data presented in the paper.

II. ARTIFACT OVERVIEW

A. Benchmark Parts

We divided the benchmark suite into two parts: a fast part that quickly generates results for reasonably sized programs and an all part that generates results for all programs. Both parts also run an exhaustive search to get the ground truth interactions if the configuration space is less than 10^7.

B. System Requirements

a) Hardware: The benchmarks presented in the paper were run on a workstation with a 64-core AMD Ryzen Threadripper 3990X @ 2.9 GHz CPU, 64 GB RAM, and at least 40GB of free disk space. Running the all benchmarks takes around 26 hours. However, the fast part could run on a normal laptop with around 8 GB RAM.

b) Software: We recommend evaluating the artifact on a Linux-based OS (tested on Ubuntu 20.04 and Debian 10.7) with Docker (tested with Docker 19.03.14 and 20.10.1). Before proceeding with the installation instructions, make sure you can successfully run the command docker run hello-world on the host machine.

# Step 1: Pull Docker image
docker pull unsatx/gentree_docker:icse21

# Step 2: Run container
docker run -it --rm --tmpfs /mnt/ramdisk \
unsatx/gentree_docker:icse21 bash

# Step 3: Run GenTree (inside container)
cd ~/gentree/wd
./gt -J2 -cx -BF @ex_paper # example
./gt -J2 -cx -BF @ex_paper --full # example (ground truth)
./gt -J2 -cx -GF 2/id # coreutils id (C)
./gt -J2 -cx -YF 2/vsftpd # vsftpd (Otter)

Fig. 1: Commands to install GenTree

C. Installation

To install the GenTree artifact, follow the instructions in Figure 1. First, we pull the pre-built Docker image from Docker Hub. If the image is not available, we can import the permanently archived image at [7]. Then, we start the container and run GenTree tool. @ex_paper is the example C program listed in Figure 2 in [1]. id and vsftpd are benchmark programs listed in Table 1 in [1].

III. GENTREE OUTPUT FORMAT

For better interoperability, the GenTree output is designed to be both human and machine-readable. For each discovered interaction, GenTree outputs a block similar to Figure 2. Blocks are separated by the line “======”. In a block, there are three components separated by the line “-”. All lines started with the character ‘#’ are comments and should be ignored while parsing. In Figure 2, the comments tell us how many hit and miss configurations classified by the
decision tree, which iteration the tree was last rebuilt, and how many configurations were used to build the tree. The first component in the block is a list of locations covered by the interaction (e.g., \( L_4 \)). The second component is an SMT-LIB 2.0 [8] formula generated by Z3 [9]. The last component is a serialized decision tree (pre-order traversal) for internal usage.

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\begin{align*}
\text{# Step 1: Check if GenTree is working.} \\
\text{# If got "Permission error", run "sudo chmod 777 -R /mnt/ramdisk" and retry.} \\
\text{./gt -J2 -cx -GF 2/id} \\
\text{# Step 2: Clean up old results} \\
\text{./scripts/bm.sh --clean} \\
\text{# Step 3:} \\
\text{# - To run the fast part (-3m on i9-9880H) } \\
\text{./scripts/bm.sh --fast --bm} \\
\text{# - To run the all part (-26h on Ryzen 3990X) } \\
\text{./scripts/bm.sh --all --bm}
\end{align*}
\]

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Fig. 3: Commands to run the benchmarks (inside container)

### IV. Evaluation

There are two parts to the evaluation process: generating interactions and analyzing them.

#### A. Generate Interactions

Follow the instructions in Figure 3 to generate the interactions and ground truths. The results are saved into files `res/<program>/a_<repeat>_full.txt`. Each program is run 11 times, so `<repeat>` is an integer from 0 to 10. The ground truth interactions, if available, are saved at `res/<program>/a_<repeat>_full.txt`. The output file format is described in §III.

#### B. Analyze Interactions

Follow the instructions in Figure 4 to analyze the generated interactions and obtain the results as presented in [1]. The analysis results are saved to `res/Analyze/<type>/<program>.csv`, where `<type>` is the analysis type (count number of each interactions type, the accuracy of inferred interactions compared to the ground truth, etc.). Each row in the `.csv` file presents the data of a single run, and the MED row at the end is the median value being reported in [1]. For a more detailed description of the analysis results, please refer to the README file in the Github source repository at [10] or the snapshot at [7].

The GenTree implementation and benchmark programs have some nondeterministic components, hence, the replicated results may not match exactly with the results in [1]. However, most of the time, they should be close or match exactly.

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### REFERENCES


